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# Advanced Delivery Timing Model Design for MPEG MMT Protocol

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#### Abstract

Maintaining timing relationships among packets in a single media stream or between packets from different media streams is an essential criterion in MMT system. It is the function of the synchronization and de-jittering algorithms to re-adjust timing relationship between the MMT packets to assure synchronized playback. Thus, delivery of time constrained MPEG media on time, according to their temporal requirements, is an important goal of MMT. For this purpose MMT needs to specify syntax and semantics of a timing model to be used by the delivery functions. In this paper, we propose a proper timestamp-related header format for MMT delivery timing model to support media synchronization in various delivery scenarios including hybrid delivery.

Keywords: delivery timing model, media delivery, MPEG media transport (MMT) protocol

#### I. Introduction

With the explosive growth of the Internet, IP (Internet Protocol)-based point-to-point communications via broad-band access have become prevalent in many industrial countries and are expected to become another important mode of communications for multimedia. On the other hand, television broadcasting via terrestrial and satellite transmission channels has been the main means for multi-

media transport for quite some time and is still an important mode of multimedia delivery. Thus it is believed that a hybrid delivery environment combining various modes of communications would enable advanced and sophisticated multimedia services [1].

The MPEG has recently developed a new standard, MPEG media transport (MMT), for the next generation hybrid media delivery service over IP networks considering the emerging convergence of digital broadcast and broadband services [2]. As an example of a hybrid content delivery environment, multimedia contents will be offered to both broadcasting channels and point-to-point communication channels based on IP networks. Some components, such as coded audio signals and coded video signals, are transported from different sources to consumer devices via different channels in the hybrid environment [3], [4]. As an example, consumer devices need to present these com-

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ponents in a synchronized manner.

In this paper, we propose a proper timestamp-related header format for MMT delivery timing model to support media synchronization in various delivery scenarios including hybrid delivery. By exploiting the delivery timing model, it is possible to maintain timing relationships among packets in a single media stream or between packets from different media streams [5], [6].

# II. Proposed Delivery Timing Model Design

### 1. Identified delivery timing information

One of the important roles of the delivery layer (D-layer) of MMT is to provide timing information generated in creating MMT packets to the receiver side for media synchronization [7]. The procedure for the creation of the MMT packets includes delivery layer packetization process. Firstly, we identify major timing parameters generated in the delivery layer packetization process. Figure 1 shows the proposed overall timing model that can be considered for the MMT system. There are five important timing instants in the proposed timing model, such as Sampling\_Time, Delivery\_Time, Arrival\_Time, Decoding\_Time, and Rendering\_Time. Sampling\_Time reflects the sampling instant of the input frame to the media encoder. The sampling instant is derived from a clock that increments monotonically

and linearly in time to allow synchronization. Considering that the RTP timestamp and DTS/PTS of MPEG-2 system commonly employ 90 kHz clock resolution for their representation, a 33-bit 90 kHz timestamp can be used to represent the Sampling Time. Delivery Time corresponds to the delivery instant of the packetized MMT packet after sender processing delay which is the elapsed time to prepare the deliverable MMT packet from Sampling Time. Arrival Time represents the arrival instant of the transmitted MMT packet at the receiver side after network transmission delay. Decoding Time corresponds to the decoding instant of the recovered compressed bitstream data for timely decoding after experiencing receiver processing delay induced by MMT delivery layer depacketization, encapsulation layer (E-layer) decapsulation, and decoder buffering delay and so on. Rendering Time designates the presentation or composition time of the reconstructed media data occurring after rendering time offset which corresponds to the time spent in a rendering buffer for frame reordering of I-, P-, B- pictures before presentation to the output devices. Rendering Time Offset is the difference between the Decoding Time and the actual presentation.

Among the above five timing instants and timing parameters, Sampling\_Time and Rendering\_Time\_Offset are determined during the media encoding and encapsulation stage performed before actual packet delivery processing including packetization, and thus can be within the scope of the encapsulation layer timing model. On the contrary,

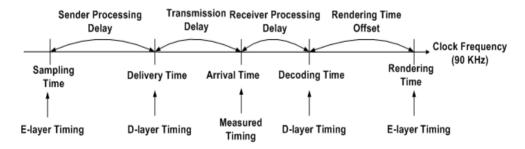


Fig. 1. Flow for hybrid delivery scenario

Delivery Time, Arrival Time, and Decoding Time are affected by the Sender Processing Delay, Transmission Delay, and Receiver Processing Delay parameters, and thus out of the scope of encapsulation layer layer timing model, but rather related to the delivery timing model. Therefore, we identify the Delivery Time, Arrival Time, and Decoding Time as the proper timing information related to the delivery timing model.

Based on the overall timing model as shown in Figure 1, Figure 2 and Figure 3 show the timing model diagram at the MMT sender and receiver sides, respectively. Data flows at a constant (or specified) rate to the encoder and the output of the encoder is at a variable rate to the encoder buffer. The constant rate output of the transmission buffer transmitted via IP networks after MMT packet packing procedure including encapsulation and delivery layer packetization processes, and into the MMT packet de-packing process after passing through the receiver buffer and then into the decoder buffer. The variable rate output of the decoder buffer is fed into the decoder to pass a constant (or specified) rate output to the decoder, then to the rendering buffer if necessary. By comparing Figure 1 with Figure 2 and Figure 3, we can notice the specific time positions of the five timing instants as well as the specific time durations of the timing parameters.

## 2. Required syntax and semantics

The syntax format and the corresponding semantics for the delivery timing information of MMT delivery layer are listed in Table 1.

# III. Usage of the Proposed Timing Instants and Parameters

Sampling Time (TSam) reflects the sampling instant of the input frame to the media encoder and it is carried in the encapsulation layer header as encapsulation layer timing information. Starting form this time instance, the timing

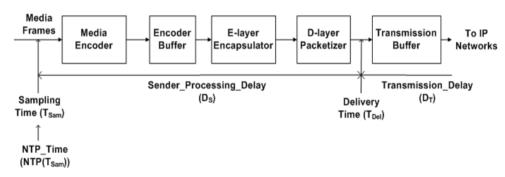


Fig. 2. Timing model diagram at the MMT sender side

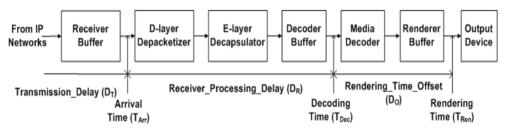


Fig. 3. Timing model diagram at the MMT receiver side

Table 1. Syntax format and semantics for the delivery timing information

instants and parameters shown in Figure 2 and Figure 3 have the following relationships:

$$\begin{split} T_{Del} &= T_{Sam} + D_S \\ T_{Arr} &= T_{Sam} + D_S + D_T \\ T_{Dec} &= T_{Sam} + D_S + D_T + D_R \, \end{split} \tag{1}$$

In addition to the above time instants, Rendering\_Time (TRen) designates the presentation or composition time of the reconstructed media data occurring after rendering time offset which corresponds to the time spent in a rendering buffer as shown in Figure 3. This Rendering\_Time is determined by the Rendering\_Time\_Offset parameter which is carried in the encapsulation layer header. Thus, among the five time instants, the three time instants shown in Eq. (1) are relevant to the scope of the delivery timing model. In order to provide continuous playback in a synchronous manner between different media streams, the total end-to-end delay occurring in the MMT system should be maintained as a constant value for all the media streams. Thus the following relationship should be observed.

$$D_{S} + D_{T} + D_{R} = D_{Tot} \tag{2}$$

The DTot consisting of Sender Processing Delay. Transmission Delay and Receiver Processing Delay should be kept constant for continuous decoding and playback at the receiver. Thus, a constant quantity equal to a proper total end-to-end delay is added, creating decoding time information as shown in Eq. (1). The DTot can be determined at the receiver considering general end-to-end transmission delay and initial latency to be experienced by the client. It could also be exchanged a priori between the receiver and the sender considering a suggested initial playback delay, for example by C.1 layer signaling, before actual starting of the MMT data transmission. It could even be adaptively adjusted based on the actual packet reception delay experienced by the receiving party. This is the reason, unlike DTS of MPEG-2 TS, why RTP which is usually used for packet transmission over IP networks does not specify any definite decoding time information its header field. The sender transmits NTP(TSam) and DS as delivery timing information by attaching the two values in the delivery layer header of MMT packet. With the provided

NTP(TSam) and DS values, UTC time in NTP format corresponding to the Delivery Time (TDel) can be recovered at the receiver as follows:

$$NTP(T_{Del}) = NTP(T_{Sam}) + D_S / 90,000$$
 (3)

The Arrival Time (TArr) can be measured after the MMT packet has arrived at the receiver terminal. If the UTC time of TArr expressed in NTP format is denoted as NTP(TArr), the transmission delay DT can be obtained as follows:

$$D_{T} = (NTP(T_{Arr}) - NTP(T_{Del})) \times 90,000$$
 (4)

From the DS and DT values, the appropriate Receiver Processing Delay (DR) is given by

$$D_{\scriptscriptstyle R} = D_{\scriptscriptstyle Tot} - (D_{\scriptscriptstyle S} + D_{\scriptscriptstyle T}) \tag{5}$$

Start Clock Offset can be derived by multiplying the CF (clock frequency) that was used to obtain the timestamp of the MMT data to the Start Time Offset as shown in the following Equation.

Start Clock Offset = Start Time Offset 
$$\times$$
 CF (6)

With the Start Clock Offset count, it is possible to derive the exact timestamp (TS) corresponding to the ABSsyn which is marked in the MMT header. The MMT packet with timestamp (TSk) is Start Clock Offset counts away (corresponding to the Start Time Offset seconds) from the first MMT packet which has timestamp of TS0. The equation for obtaining TSk is shown in Equation 7.

$$TS_k = TS_0 + Start \quad Clock \quad Offset$$
 (7)

With this DR value, the receiver can identify the exact

time duration that the compressed media data (i.e. Access Unit) should spend in the decoder buffer before it is decoded. By observing this process, the delivered MMT packet can be decoded at exact Decoding Time instant, thus providing perfect media synchronization between several media sources even delivered by different servers via different networks or channels. Note that RTP does not give any information on the amount of buffering that may be needed at the receiver, or the decoding time of the packets.

In (9), The timing information DS value can also be used to more accurately measure the amount of packet arrival jitter. In RTP, the interarrival jitter is defined to be the mean deviation of the difference in the packet spacing at the receiver compared to the sender for a pair of packets. Because the jitter calculation is based on the RTP timestamp which represents the instant when the first data in the packet was sampled, any variation in the delay between that sampling instant and the time the packet is transmitted will affect the resulting jitter that is calculated. Such a variation in delay would occur for audio packets of varying duration. It will also occur for video encodings because the timestamp is the same for all the packets of one frame but those packets are not all transmitted at the same time. The variation in delay until transmission does reduce the accuracy of the jitter calculation as a measure of the behavior of the network by itself. Unlike the conventional case of jitter calculation, in the proposed timing model, Delivery Time corresponding to the exact delivery instant is used for interarrival jitter calculation. This may result in more accurate estimation of the required de-jitter buffering time which corresponds to the sufficient size of the receiver buffer in Figure 3. Note that the proposed delivery timing mechanism can be applied to both GOP structure of IPPPP and IBBPBBP. The purpose of such kind of de-jitter buffering is to recover the temporal relationship between MMT packets arriving with different timing at the buffer

output. Under this approach, we can adequately remove jitter induced by IP networks and forward the de-jittered MMT packets to the MMT receiver processing side. The detailed procedure of how the receiver client does the jitter calculation would be out of the scope of the MPEG standard.

#### IV Conclusions

In this paper, we identified relevant delivery timing parameters for MMT and proposed a proper timestamprelated header format for MMT delivery timing model to support media synchronization in various delivery scenarios including hybrid delivery.

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